An inversion tool for conditional term rewriting systems - a case study of Ackermann inversion

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An Inversion Tool for Conditional Term Rewriting Systems
– A Case Study of Ackermann Inversion

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We report on an inversion tool for a class of oriented conditional constructor term rewriting systems. Four well-behaved rule inverters ranging from trivial to full, partial and semi-inverters are included. Conditional term rewriting systems are theoretically well founded and can model functional and non-functional rewrite relations. We illustrate the inversion by experiments with full and partial inversions of the Ackermann function. The case study demonstrates, among others, that polyvariant inversion and input-output set propagation can reduce the search space of the generated inverse systems.

Keywords  program inversion, program transformation, term rewriting systems, case study

1 Introduction

Program inversion is one of the fundamental transformations that can be performed on programs \cite{3}. Although function inversion is an important concept in mathematics, program inversion has received little attention in computer science. In this paper, we report on a tool implementation of an inversion framework \cite{6} and on some computer experiments within the framework. The implementation includes four well-behaved rule inverters ranging from trivial to full, partial and semi-inverters, several of which have been studied in the literature \cite{7,12,13}. The generic inversion algorithm used by the tool was proven to produce the correct result for all well-behaved rule inverters \cite{6}. The tool reads the standard notation of the established confluence competition (COCO), making it compatible with other term rewriting tools. The Haskell implementation is designed as an open system for experimental and educational purposes that can be extended with further well-behaved rule inverters.

In particular, we illustrate the use of the tool by repeating A.Y. Romanenko’s three experiments with full and partial inversions of the Ackermann function \cite{15,16}. His inversion algorithm, inspired by Turchin \cite{17}, inverts programs written in a Refal extension, Refal-R \cite{16}, which is a functional-logic language, whereas our tool uses a subclass of oriented conditional constructor term rewriting systems\cite{1,14} (CCSs) \cite{1,14}. Conditional term rewriting systems are theoretically well founded and can model a wide range of language paradigms, e.g., reversible, functional, and declarative languages.

Let us illustrate our tool with three kinds of inversions of a simple `remove-index` function, `rem` (Figure 1). Given a list and a unary number \( n \), it returns the \( n \)th element of the list and the list without the removed element. `rem` is defined by two rewrite rules: the first rule defines the base case where `cons (:)` is written in prefix notation and the two outputs are tupled (`<`). The second rule contains a so-called condition after the separator (`<=`) that can be read as a recursion. The input-output relation specified by `rem` is exemplified by the list \([a,b,b]\) and the indices 0, 1, and 2 (inputs are marked in blue).

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\[^{1}\]CCSs are also referred to as pure constructor CTRS \cite{10}.
We begin by giving an overview of the tool (Section 2) followed by the case study of Ackermann inversion (Section 3). This paper, the tool implementation itself, and the paper on the inversion framework are intended to complement each other. They are intended to be used together. For more details on the generic inversion algorithm and the rule inverters, interested readers are therefore referred to [6].
2 Inversion Tool

The tool is implemented in Haskell\footnote{The Glorious Glasgow Haskell Compilation System, version 8.10.4} and we provide both an online web-based version\footnote{https://topps.di.ku.dk/pirc/inversion-tool} and the source code\footnote{https://github.com/pirc-src/inversion-tool}. We demonstrate how to partially invert a function add, which defines the addition of two unary numbers, to obtain $\text{add}\{1\}\{1\}$, which defines the subtraction of two unary numbers. As illustrated in Figure 2, the Inversion Framework requires three inputs: (i) the original CCS rules with the add-rules, (ii) the Inversion task: add with io-set $I = \{1\}$ and $O = \{1\}$, and (iii) an indication of which well-behaved Rule inverter the tool should apply, here, the partial rule inverter. The inversion framework provides two outputs: (i) the Inverted CCS rules, containing the $\text{add}\{1\}\{1\}$-rules defining subtraction, and (ii) a Diagnostics table with an overview of the systems’ paradigm characteristics. Because the program inversion does not respect language paradigms, it is useful that the tool also provides an analysis of the programs’ paradigm characteristics; see \cite{6} Fig.2 for definitions and interrelations.

Whereas the source code provides a command line interface, which facilitates composition with other program transformations, the online web-based version provides a friendly clickable interaction; see Figure 3 for a screenshot. In the following, we describe the most important content and features of the online tool. The tool web-site contains the following:

1. a navigation bar (in the top) with green action buttons and white settings buttons,
2. a white input window with a text field for the original CCS,
3. a gray output window (in the lower left corner) for the inverted systems, and
4. another gray output window (in the lower right corner) with program diagnostics.

The original CCS can either be entered into the input window or chosen from the predefined CCS examples available via the Examples button, e.g., choosing add. Using the Options button, one defines the inversion task, e.g., the partial inversion of add with $I = \{1\}$ and $O = \{1\}$ and selects one of the rule inverters, e.g., the partial rule inverter. To apply the inverter, we use the Invert button whereafter the tool
3 A Case Study of Ackermann Inversion

We illustrate the use of our tool by repeating three experiments \cite{16}, namely, two partial inversions and a full inversion of the Ackermann function \texttt{ack} (Figure 4a). \texttt{ack} takes two unary numbers as inputs and returns one unary number as output.

**First Experiment** An io-set together with the \texttt{ack} program in Figure 4a are the tool inputs. The io-set for this experiment is \( I = \{ 1 \} \) and \( O = \{ 1 \} \), specifying that the first input term and the output term of \texttt{ack} are the inputs for the partially inverted program \texttt{ack}\{1\}\{1\}. Then, our tool propagates the io-set through the entire program and transforms the rules locally using the selected well-behaved rule inverter.

The result of the pure partial inversion \cite[Fig.6]{6} is shown in Figure 4b. The resulting program

...
ack(0, y) -> <s(y)>
ack(s(x), 0) -> <z> <= ack(x, s(0)) -> <z>
ack(s(x), s(y)) -> <z> <= ack(s(x), y) -> <v>, ack(x, v) -> <z>

(a) Program ack implementing the Ackermann function Ack(x, y).

ack{1}{1}(0, s(y)) -> <y>
ack{1}{1}(s(x), z) -> <0> <= ack{1,2}{1}(x, s(0), z) -> <>
ack{1}{1}(s(x), z) -> <s(y)> <= ack{1}{1}(x, z) -> <v>,
ack{1}{1}(s(x), v) -> <y>
ack{1,2}{1}(0, y, s(y)) -> <>
ack{1,2}{1}(s(x), 0, z) -> <> <= ack{1,2}{1}(x, s(0), z) -> <>
ack{1,2}{1}(s(x), s(y), z) -> <> <= ack{1}{1}(x, z) -> <v>,
ack{1,2}{1}(s(x), y, v) -> <>

(b) Partial inverse of ack with I = {1} and O = {1}.

ack_2(0, s(y)) -> <y>
ack_2(s(x), z) -> <0> <= ack_2(x, z) -> <s(0)>
ack_2(s(x), z) -> <s(y)> <= ack_2(x, z) -> <v>,
ack_2(s(x), v) -> <y>

(c) Romanenko’s partial inverse Ack_{2}^{-1} [16, p.17] rewritten as a CCS.

Figure 4: Partial inversions of the Ackermann function and the dependency graphs.
to use fewer rewriting steps because its call to ack{1,2}{1} can fail using pattern matching, whereas ack_2 requires a rewriting and pattern match of the result to establish the same failure.

The number of required rewrite steps is used in the complexity of conditional term rewriting systems [8], and the number of function/predicate calls is used in the complexity analysis of functional and logic programs [9, 11]. Here, function calls correspond to the number of function-rooted terms that must be rewritten to reach normal form.

To confirm that these speed-ups manifest themselves in a functional-logic language, we implemented ack{1}{1} and ack_2 in Curry and measured their runtimes in CPU seconds on input (3,253) using two Curry systems \(^5\). The Haskell-based Kics2 terminated on the programs after 1295.7 s and 4674.6 s, respectively, and the Prolog-based Pakcs3 terminated after 8.5 s and 40.7 s, respectively. Thus, the speed-ups in Curry, which are 3.61 and 4.79, are comparable to the speed-ups for function calls and rewrite steps.

On the other hand, the polyvariant io-set propagation also has a cost with respect to the size of ack{1}{1}: in the worst case, all possible inversions of a function symbol are created–io-sets are never

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\(^5\)The programs were executed using the Docker images caups/pakcs3:3.3.0 and caups/kics2:2.3.0 on an Apple MacBook Pro (2.6 GHz 6-Core Intel Core i7 processor, 16 GB memory, Intel Graphics). The execution times are slower than if Curry were installed directly on the machine, but the relative program execution times are expected to hold in either case.

<table>
<thead>
<tr>
<th>Input</th>
<th>(1, 2)</th>
<th>(1, 3)</th>
<th>(1, 4)</th>
<th>(1, 5)</th>
<th>(1, 6)</th>
<th>(1, 7)</th>
<th>(1, 8)</th>
</tr>
</thead>
<tbody>
<tr>
<td>ack_2</td>
<td>Rewrite steps</td>
<td>5</td>
<td>8</td>
<td>11</td>
<td>14</td>
<td>17</td>
<td>20</td>
</tr>
<tr>
<td></td>
<td>Function calls</td>
<td>9</td>
<td>12</td>
<td>15</td>
<td>18</td>
<td>21</td>
<td>24</td>
</tr>
<tr>
<td>ack{1}{1}</td>
<td>Rewrite steps</td>
<td>4</td>
<td>6</td>
<td>8</td>
<td>10</td>
<td>12</td>
<td>14</td>
</tr>
<tr>
<td></td>
<td>Function calls</td>
<td>9</td>
<td>12</td>
<td>15</td>
<td>18</td>
<td>21</td>
<td>24</td>
</tr>
<tr>
<td><strong>Speed-up</strong></td>
<td>Rewrite steps</td>
<td>1.25</td>
<td>1.33</td>
<td>1.38</td>
<td>1.40</td>
<td>1.42</td>
<td>1.43</td>
</tr>
<tr>
<td></td>
<td>Function calls</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
</tr>
</tbody>
</table>

Table 1: The rewrite steps and function calls for ack{1}{1} and ack_2 on a range of inputs.
ack\{2\}{1}(y, s(y)) -> <0
ack\{2\}{1}(0, z) -> <s(x)> <= ack\{2\}{1}(s(0), z) -> <x>
ack\{2\}{1}(s(y), z) -> <s(x)> <= ack\{1\}{1}(z) -> <x, v>,
                            ack\{1,2\}{1}(s(x), y, v) -> < >

ack\{1\}{1}(s(y)) -> <0, y>
ack\{1\}{1}(z) -> <s(x), 0> <= ack\{2\}{1}(s(0), z) -> <x>
ack\{1\}{1}(z) -> <s(x), s(y)> <= ack\{1\}{1}(z) -> <x, v>,
                            ack\{1\}{1}(s(x), v) -> <y>

(a) Partial inverse of ack with I = \{2\} and O = \{1\} includes, in addition, the rules of Figure 4b:

ack_1(y, s(y)) -> <0
ack_1(0, z) -> <s(x)> <= ack_1(s(0), z) -> <x>
ack_1(s(y), z) -> <s(x)> <= ack_0(z) -> <s(x), v>,
                            ack_1(s(y), v) -> <s(x), y>

ack_0(s(y)) -> <0, y>
ack_0(z) -> <s(x), 0> <= ack_0(z) -> <x, s(0)>
ack_0(z) -> <s(x), s(y)> <= ack_0(z) -> <x, v>,
                            ack_0(v) -> <s(x), y>

(b) Romanenko’s partial inverse Ack\_1\_1 \[16, p.17\] rewritten as a CCS.

(c) Dependency graphs of ack\{2\}{1} and ack_1.

Figure 5: A partial inversion of the Ackermann function and the dependency graphs.

generalized—thereby increasing the size of the generated program. Despite the full propagation of the
io-sets, the tool always terminates due to their finite number for any program; this characteristic relates
to mode analysis \[14\]. Romanenko’s method, which is potentially more powerful due to the global
approach because it builds a configuration graph and uses generalization to make the unfolding of calls
terminate, produces a monovariant partial inverse ack_2 so that not all known local information is used
(Figure 4c); this may be due to the generalization in the configuration graph \[15\].

Second experiment The next experiment is the partial inversion ack\{2\}{1} and our tool correctly
produces the inverse that defines four function symbols including ack\{1\}{1} and ack\{1,2\}{1} and also
a full inverse ack\{\}\{1\}. This full inverse depends on the partial inverses ack\{1\}{1} and ack\{2\}{1}
due to the io-set propagation in our tool. By contrast, Romanenko’s partial inversion ack_1 depends on
itself and on ack_1’s full inverse ack_0. His full inverse depends on itself \[16\ p.17\] instead of partial
inverses that would have been possible if all known information was exploited. Both systems ack\{2\}{1}
and ack_1 are shown in Figure 5a and 5b, where ack\{2\}{1} depends on ack\{1,2\}{1} and ack\{1\}{1}
in Figure 4b. The systems are illustrated by their dependency graphs in Figure 5c.

Romanenko’s ack_1 and ack\{2\}{1} are nonterminating. The third rule of ack_0 has ack_0(z)
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\begin{align*}
\text{ack}\{1\}(s(y)) & \rightarrow <0, y> \\
\text{ack}\{1\}(z) & \rightarrow <s(x), 0> \quad \leq \quad \text{ack}\{1\}(z) & \rightarrow <x, s(0)> \\
\text{ack}\{1\}(z) & \rightarrow <s(x), s(y)> \quad \leq \quad \text{ack}\{1\}(z) & \rightarrow <x, v>, \\
& \quad \text{ack}\{1\}(v) & \rightarrow <s(x), y>
\end{align*}

Figure 6: The full inverse of the Ackermann function.

as its left-hand side and also requires a rewriting of the same term \text{ack}_0(z) in its first condition, thus yielding an infinitely deep search tree. The third rule of \text{ack}\{1\} has a similar structure. Since both programs are nonterminating, no counts are provided. Nevertheless, when producing \text{ack}\{2\}, our tool discovers an improvement of the inverse system, e.g., the second condition of the third rule depends on the terminating \text{ack}\{1,2\} whereas the same condition of the same rule of \text{ack}_1 depends on the nonterminating \text{ack}_1.

The cost of creating polyvariant inversions is evident in \text{ack}\{2\}, where the tool has created 4 different inversions of the 3 original rules, producing a system of 12 rules. In comparison, \text{ack}_1 consists of two inversions of the same three original rules producing a smaller system of 6 rules; see the dependency graphs in Figure 5c.

**Third experiment** In the third experiment, Romanenko used his full inverter \cite[Sect.3.1]{Romanenko} to invert \text{ack}, and our pure full inverter \cite[Fig.6]{our_tool} produces exactly the same program, namely, \text{ack}\{1\}, in Figure 6. Please note that this full inversion shares the same defined function symbol as the rules in Figure 5 but the rules are different. This is because they define the same input-output relation, namely, the full inversion of the original \text{ack}. This system is nonterminating; thus, no count is provided. By exploiting the mathematical property of Ackermann that its output is larger than its input, it may be possible to create a terminating full inversion. It is beyond the tool to use extra mathematical properties to improve the inversions.

The fourth partial inversion that is possible is \text{ack}\{1,2\}, which is already included in Figure 4b. This means that with our tool, we produced all four possible partial inversions (including the special case of full inversion) of the Ackermann function in the course of the three experiments. Using our tool, we also reproduced all of the examples in \cite{our_tool, our_tool2}.

### 4 Conclusion and Future Work

The goal of this work was to provide a design space for the experimental evaluation and comparison of different well-behaved rule inverters, including those using heuristic approaches \cite{our_tool2}. It will be interesting to investigate Romanenko’s inversion method \cite{Romanenko} as well as related global approaches \cite{global1, global2, global3} and program analyses such as mode and binding-time analyses. Using CCSs enabled us to focus on the essence of inversion without considering language-specific details, as demonstrated by the examples above. The examples demonstrate that polyvariant inversion can considerably reduce the search space of the inverted system. The post-optimizations of the inverted programs represent another future direction of investigation. We have observed two potential improvements: the first is the reduction of nondeterminism by determinization \cite[10]{our_tool}, and the other is exploiting constants by partial evaluation, for example, the constant \textit{s}(0) of the 2nd rule of Figure 4b. We expect that this will further improve the efficiency of inverse systems. In future work, one can consider the translation of the resulting programs to logic or functional-logic programming languages, such as Prolog or Curry, and explore the relation to partial deduction in logic programming.
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References


