Measurement of Atmospheric Neutrino Oscillations at 6-56 GeV with IceCube DeepCore


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Measurement of Atmospheric Neutrino Oscillations at 6–56 GeV with IceCube DeepCore


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We present a measurement of the atmospheric neutrino oscillation parameters using three years of data from the IceCube Neutrino Observatory. The DeepCore infill array in the center of IceCube enables the detection and reconstruction of neutrinos produced by the interaction of cosmic rays in Earth’s atmosphere at energies as low as ~5 GeV. That energy threshold permits measurements of muon neutrino disappearance, over a range of baselines up to the diameter of the Earth, probing the same range of \( L/E_\nu \) as

\[ L/E_\nu \sim 5 \text{ GeV} \]
**Introduction.**—It is well established that the neutrino mass eigenstates do not correspond to the neutrino flavor eigenstates, leading to flavor oscillations as neutrinos propagate through space [1,2]. After traveling a distance $L$, a neutrino of energy $E$ may be detected with a different flavor than it was produced with. In particular, the muon neutrino survival probability is described approximately by

$$P(\nu_\mu \rightarrow \nu_\mu) \approx 1 - 4|U_{\mu 3}|^2(1 - |U_{\mu 3}|^2)\sin^2 \left(\frac{\Delta m^2_{32}L}{4E}\right),$$

where $U_{\mu 3} = \sin \theta_{23} \cos \theta_{13}$ is one element of the Pontecorvo-Maki-Nakagawa-Sakata [3,4] matrix $U$ expressed in terms of the mixing angles $\theta_{23}$ and $\theta_{13}$, and $\Delta m^2_{32} = m_3^2 - m_2^2$ is the splitting of the second and third neutrino mass states that drives oscillation on the length and energy scales relevant to this analysis. In addition to the parameters shown in Eq. (1), neutrino oscillations also depend on the parameters $\theta_{12}$, $\Delta m^2_{12}$, and $\delta_{CP}$, but these have a negligible effect on the data presented in this paper.

Interactions of cosmic rays in the atmosphere [5–7] provide a large flux of neutrinos traveling distances ranging from $L \sim 20$ km (vertically down-going) to $L \sim 1.3 \times 10^4$ km (vertically up-going) to a detector near the Earth’s surface. For up-going neutrinos, there is complete muon neutrino disappearance at energies as high as $\sim 25$ GeV. Given the density of material traversed by these neutrinos, matter effects alter Eq. (1) slightly and must be taken into account [8–11].

In this Letter, we report our measurement of $\theta_{23}$ and $\Delta m^2_{32}$, using the IceCube Observatory to observe oscillation-induced patterns in the atmospheric neutrino flux coming from all directions between 5.6 GeV and 56 GeV. The results presented here complement other leading experiments [12–16] in two ways. Long-baseline experiments with baselines of a few hundred kilometers and Super-Kamiokande observe much lower-energy events [primarily charged-current quasielastic (CCQE) and resonant scattering], while our measurement relies on higher-energy deep inelastic scattering events and is thus subject to different sources of systematic uncertainty [17]. In addition, the higher-energy range of IceCube neutrinos provides complementary constraints on potential new physics in the neutrino sector [18–27].

The IceCube detector was fully commissioned in 2011, and we previously reported results [28] using data from May 2011 through April 2014. Those results were obtained using reconstruction tools that relied on unscattered Cherenkov photons and therefore were less susceptible to detector noise. The results presented here use a new reconstruction that includes scattered photons and retains an order of magnitude more events per year. Because the detector’s noise rates were still stabilizing during the first year of operation, and the new reconstruction is more susceptible to noise, we chose before unblinding to use data from April 2012 through May 2015.

**The IceCube DeepCore detector.**—The IceCube In-Ice Array [29] is composed of 5160 downward-looking 10 in. photomultiplier tubes (PMTs) embedded in a 1 km$^3$ volume of the South Pole glacial ice at depths between 1.45 and 2.45 km. The PMTs and associated electronics are enclosed in glass pressure spheres to form digital optical modules (DOMs) [30,31]. The DOMs are deployed on 86 vertical strings of 60 modules each. Of these strings, 78 are deployed in a triangular grid with horizontal spacing of about 125 m between strings. These DOMs are used primarily as an active veto to reject atmospheric muon events in this analysis. The remaining eight strings fill a more densely instrumented $\sim 10^7$ m$^3$ volume of ice in the bottom center of the detector, called DeepCore, enabling detection of neutrinos with energies down to $\sim 5$ GeV [32].

Neutrino interactions in DeepCore are simulated with GENIE [33]. Hadrons produced in these interactions are simulated using GEANT4 [34], as are electromagnetic showers below 100 MeV. At higher energies, shower-to-shower variation is small enough to permit the use of standardized light emission templates [35] based on GEANT4 simulations to reduce computation time. Muons’ energy losses in the ice are simulated using the PROPOSAL package [36]. Cherenkov photons produced by showers and muons are tracked individually using GPU-based software to simulate scattering and absorption [37].

**Reconstruction and event selection.**—The event reconstruction used in this analysis models the scattering of Cherenkov photons in the ice surrounding our DOMs [38] to calculate the likelihood of the observed photor-electrons as a function of the neutrino interaction position, direction, and energy. Given the complexity of this likelihood space, the MultiNest algorithm [39] is used to find the global maximum. This reconstruction is run under two different event hypotheses: first with a $\nu_\mu$ charged-current (CC) interaction comprising a hadronic shower and collinear muon track emerging from the interaction vertex, and then with only a shower at the vertex (i.e., a nested

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hypothesis with zero muon track length). The latter model incorporates \( \nu_e \) and most \( \nu_\mu \) CC interactions as well as neutral current (NC) interactions, as we do not attempt to separate electromagnetic showers produced by a leading lepton from hadronic showers produced by the disrupted nucleus.

The \( \nu_\mu \) CC reconstruction is used to estimate the direction and energy of the neutrino. The difference in best-fit likelihoods between the two hypotheses is used to classify our events as “track-like,” if inclusion of a muon track improves the fit substantially, or “cascade-like,” if the event is equally well fit without a muon. The reconstructed neutrino energy \( (E_{\text{rec}}) \) distributions of events in each of these categories after final selection are shown in Fig. 1, along with the corresponding predicted distributions broken down by event type. The track-like sample is enriched in \( \nu_\mu \) CC events (68% of sample), especially at higher energies where muons are more likely detected, while the cascade-like sample is evenly divided between \( \nu_\mu \) CC and interactions without a muon in the final state. The angular and energy resolutions provided by the reconstruction are energy dependent, with median resolutions of \( 10^6 \) (16°) in zenith angle and 24% (29%) in neutrino energy for track-like (cascade-like) events at \( E_\nu = 20 \text{ GeV} \).

The event selection in this analysis uses the DOMs surrounding the DeepCore region to veto atmospheric muons. The first criteria remove accidental triggers caused by dark noise by demanding a minimum amount of light detected in the DOMs outside DeepCore, in a time window consistent with atmospheric muons penetrating to the fiducial volume, are then rejected. These are followed by a boosted decision tree (BDT) [40] which further reduces the background of atmospheric muons. The BDT uses the timing and spatial scale of the detected photoelectrons to select events with substantial charge deposition at the beginning of the event, indicative of a neutrino interaction vertex. It also considers how close the event is to the border of the DeepCore volume and the results of several fast directional reconstructions [41] in determining whether the event may be an atmospheric muon. Finally, we demand that the interaction vertex reconstructed by the likelihood fit described above be contained within DeepCore and that the end of the reconstructed muon be within the first row of DOMs outside DeepCore, which further reduces atmospheric muon contamination and improves reconstruction accuracy.

As these selection criteria reduce the atmospheric muon rate by a factor of approximately \( 10^8 \), it is challenging to simulate enough atmospheric muons to obtain a reliable prediction for the distribution of the remaining muons, especially in the presence of systematic uncertainties. We instead use a data-driven estimate of the shape of the muon background distributions, with the normalization free to float. This approach is based on tagging events that would have been accepted except for a small number of photons detected in the veto region, similar to the procedure in Ref. [28]. The uncertainty in the background shape is estimated using two different criteria for tagging these events, and was compared to the currently available muon Monte Carlo simulations. This uncertainty is added in quadrature to the statistical uncertainties in the tagged background event sample and the neutrino Monte Carlo simulations, to provide the total uncorrelated statistical uncertainty \( (\sigma_{\nu_\mu}^{\text{uncor}}) \) in the expected distribution shown in Fig. 1.

Analysis.—The final fit of the data is done using an \( 8 \times 8 \times 2 \) binned histogram, with eight bins in \( \log_{10} E_{\text{rec}, \text{data}} \), eight bins in the cosine of the reconstructed neutrino zenith direction \( (\cos \theta_{\nu, \text{rec}}) \), one track-like bin, and one cascade-like bin. The bins are equally spaced with \( \cos \theta_{\nu, \text{rec}} \in [-1, 1] \) and \( \log_{10} E_{\text{rec}, \text{data}} \in [0.75, 1.75] \). The fit assumes three-flavor oscillations with \( \Delta m^2_{21} = 7.53 \times 10^{-5} \text{ eV}^2 \), \( \sin^2 \theta_{12} = 0.304 \), \( \sin^2 \theta_{13} = 2.17 \times 10^{-2} \), and \( \Delta \nu_{CP} = 0^\circ \).

We use MINUIT2 [42] to minimize a function

\[
\chi^2 = \sum_{i \in \text{bins}} \frac{(n_i^{\nu_\mu} - n_i^{\text{data}})^2}{(\sigma_i^{\nu_\mu})^2 + (\sigma_i^{\nu_\mu})^2} + \sum_{j \in \text{syst}} \frac{(s_j - \hat{s}_j)^2}{\sigma_j^2},
\]

where \( n_i^{\nu_\mu} \) is the number of events expected in the \( i \)th bin, which is the sum of neutrino events weighted to the desired oscillation parameters using PROBS++ [43] and the atmospheric muon background. The number of events observed in the \( i \)th bin is \( n_i^{\text{data}} \), with Poisson uncertainty

![FIG. 1. Reconstructed energy distributions observed in data (points) and predicted by interaction type at our best-fit point for oscillations (stacked). In addition to each separate component, the uncorrelated statistical uncertainty associated with the expectation \( (\sigma_{\nu_\mu}^{\text{uncor}}) \) is shown in a shaded band. The track-like sample is peaked at higher energy due to the rising probability of tagging \( \nu_\mu \) CC events. The bottom plots show the ratio of the data to the fitted prediction.](image-url)
to unrelated atmospheric muons detected in the veto volume. This last effect is expected to reduce the neutrino rate by several percent, but it is not included in the present simulation. A prior of \( \sigma_s = 0.10 \) is placed on the spectral index to describe the range of these uncertainties.

Several uncertainties on the DIS cross section were implemented in the fit, but found either to have negligible impact or to be highly degenerate with the normalization and spectral index parameters over the energy range of this analysis. These include values of parameters of the Bodek-Yang model \([44]\) used in \textsc{genie}, uncertainties in the differential DIS cross section, and hadronization uncertainties for high-\( W \) DIS events \([45]\). As these effects are captured by the first two nuisance parameters, the additional parameters were not used.

One neutrino cross-section uncertainty was not well described by these parameters: the uncertainty of the axial mass form factor for resonant events. The default value of \( \gamma = -2.66 \) at the relevant energies in our neutrino flux model \([7]\) or the deep inelastic scattering (DIS) cross section. A prior of \( \sigma_s = 0.10 \) is placed on the spectral index to describe the range of these uncertainties.

The analysis includes 11 nuisance parameters describing our systematic uncertainties, summarized in Table I. Seven of these are related to systematic uncertainties in the atmospheric neutrino flux and interaction cross sections. Since only the event rate is observed directly, some uncertainties in flux and cross section have similar effects on the data. In these cases, the degenerate effects are combined into a single parameter. Because analytical models of these effects are available, these parameters can be varied continuously by reweighting simulated events.

The first nuisance parameter is the overall normalization of the event rate. It is affected by uncertainties in the atmospheric neutrino flux and the neutrino interaction cross section, and by the possibility of accidentally vetoing neutrino events due to unrelated atmospheric muons detected in the veto volume. This last effect is expected to reduce the neutrino rate by several percent, but it is not included in the present simulations. Because of this and the fact that it encompasses several effects, no prior is used for this parameter.

<table>
<thead>
<tr>
<th>Parameters</th>
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</thead>
<tbody>
<tr>
<td>Best fit</td>
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<td></td>
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<tr>
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<td>85</td>
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<td>125</td>
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<tr>
<td>NC relative normalization [%]</td>
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<td>106</td>
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<tr>
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<tr>
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</table>
photons near the DOMs, modulating the relative optical efficiency as a function of the incident photon angle. The effect of the refrozen ice column is modeled by two effective parameters controlling the shape of the DOM angular acceptance curve.

The first parameter controls the lateral angular acceptance (i.e., relative sensitivity to photons traveling roughly 20° above versus below the horizontal) and is fairly well constrained by LED calibration data. Five MC data sets were generated covering the $-1\sigma$ to $+1\sigma$ uncertainty from the LED calibration, and were parametrized in the same way as the overall optical efficiency described above. A Gaussian prior based on the LED data is used.

The second parameter controls sensitivity to photons traveling vertically upward and striking the DOMs head on, which is not well constrained by string-to-string LED calibration. That effect is modeled using a dimensionless parameter ranging from $-5$ (corresponding to a bubble column completely obscuring the DOM face for vertically incident photons) to 2.5 (no obscuration). Zero corresponds to constant sensitivity for angles of incidence from 0° to 30° from vertical. Six MC sets covering the range from $-5$ to 2 were used to parametrize this effect. No prior is applied to this parameter due to lack of information from calibration data.

The last nuisance parameter controls the level of atmospheric muon contamination in the final sample. As described above, the shape of this background in the analysis histogram, including binwise uncertainties, is derived from data. Since the absolute efficiency for tagging background events with this method is unknown, the normalization of the muon contribution is left free in the fit.

An illustration of how these nuisance parameters are constrained in the fit is provided as Supplemental Material [47] to this Letter. In addition to the systematic uncertainties discussed above, we have considered the impact of seed dependence in our event reconstruction, different optical models for both the undisturbed ice and the refrozen ice columns, and an improved detector calibration currently being prepared. In all these cases the impact on the final result was found to be minor, and they were thus omitted from the fit and the error estimate.

Results and conclusion.—The analysis procedure described above gives a best fit of $\Delta m^2_{32} = 2.31^{+0.14}_{-0.13} \times 10^{-3}$ eV$^2$ and $\sin^2 \theta_{23} = 0.51^{+0.07}_{-0.09}$, assuming normal neutrino mass ordering (NO). For the inverted mass ordering (IO), the best fit shifts to $\Delta m^2_{32} = -2.32 \times 10^{-3}$ eV$^2$ and $\sin^2 \theta_{23} = 0.51$. The pulls on the nuisance parameters are shown in Table I. Though IceCube’s current sensitivity to the mass ordering is low, dedicated analyses are underway to measure this.

The data agree well with the best-fit MC data set, with $\chi^2 = 117.4$ for both neutrino mass orderings. This corresponds to a $p$ value of 0.52 given the 119 effective degrees of freedom estimated via toy MCs, following the procedure described in Ref. [27].

To better visualize the fit, Fig. 2 shows the results of the fit projected onto a single $L/E$ axis, for both the track-like and cascade-like events. The two peaks in each distribution correspond to down-going and up-going neutrino trajectories. Up-going $\nu_\mu + \bar{\nu}_\mu$ are strongly suppressed in the track-like channel due to oscillations. Some suppression of up-going cascade-like data is also visible, due to the disappearance of lower-energy $\nu_\mu$ which are not tagged as track-like by our reconstruction.

Figure 3 shows the region of $\sin^2 \theta_{23}$ and $\Delta m^2_{32}$ allowed by our analysis at 90% C.L., along with our best fit and several other leading measurements of these parameters [12–14,16]. The contours are calculated using the approach of Feldman and Cousins [48] to ensure proper coverage.

Our results are consistent with those from other experiments [12–16], but using significantly higher-energy neutrinos and subject to a different set of systematic uncertainties. Our data prefer maximal mixing, similar to the result from T2K [13]. The best-fit values from the NO$\nu$A experiment [14] are disfavored by $\Delta \chi^2 = 8.9$ (first octant) or $\Delta \chi^2 = 8.8$ (second octant), corresponding to a significance of $2.6\sigma$ using the method of Feldman and Cousins, although there is considerable overlap in the 90% confidence regions of the two measurements. Further improvements to our analysis are underway, including the incorporation of additional years of data, extensions of our event selections, and improved calibration of the detector response.
FIG. 3. The 90% allowed region from this work (solid line) compared to other experiments [12–14,16] (dashed lines). The cross marks our best-fit point. The outer plots show the results of the 1D projections after profiling over the other variables along with the 68% C.L. \( \Delta \chi^2 \) threshold estimated using the Feldman-Cousins method [48].

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